



# Introduction of Distributed System

*Sungyoung Lee*  
*College of Engineering*  
*KyungHee University*




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# Introduction

- **Computer Systems are under going a revolution**  
**From 1945 until about 1985,**
  - Computers were large & expensive
  - Lack of a way to connect them  
(operated independently from one another)
- **In the Mid-80'**
  - Powerful microprocessors are developed
  - High-speed computer networks are invented
  - Not only feasible, but easy to put together computing systems composed of large number of computers connected by a high-speed network
  - They are called computer networks or distributed systems  
(in contrast to the previous centralized systems)



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## 1.1. Definition of a Distributed System

- “A Distributed system is a collection of independent computers that appears to its users as a single coherent system”
- **Two aspect**
  - Hardware: the machines are autonomous
  - Software: the users think they are dealing with a single system
- **Characteristics**
  - Differences between the various computers and the ways in which they communicate are hidden from users
  - Users and applications can interact with a distributed system in a consistent and uniform way, regardless of where and when interaction takes place

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## 1.1. Definition of a Distributed System

- **Characteristics**
  - Relatively easy to expand or scale
  - Normally be continuously available  
(although certain parts may be temporarily out of order)
  - Offering a single system view : **→ Middleware**  
(in heterogeneous environments)

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## 1.2. Goals

- A distributed system **should easily connect users to resources;**
- it should **hide the fact that resources** are distributed across a network
- it **should be open**
- and it **should be scalable**

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### 1.2.1 Connecting Users and Resources

- **Is to make it easy for users to access remote resources, and to share them with other users in a controlled way**
  - Reason for sharing resources: economics
- **Easier to collaborate and exchange information**
  - Internet, groupware
- **Security** is becoming more and more important as connectivity and sharing increase
  - Tracking communication to build up a preference profile of a specific user

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## 1.2.2. Transparency

- Is to hide the fact that its processes and resources are physically distributed across multiple computers → transparent

### ① access transparency

: **hiding differences in data representation and how a resource is accessed**

- Ex) to send an integer from intel-based workstation to SUN SPARC machine
- Ex) different naming convention

### ② location transparency

: **users cannot tell where a resource is physically located in the system** → “naming”

- Ex) assigning only logical names to resources

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## 1.2.2. Transparency

### ③ migration transparency

: **resources can be moved without affecting how that resource can be accessed**

### ④ relocation transparency

: **resources can be relocated while they are being accessed without the user or application noticing anything**

- Ex) when mobile users can continue to use their wireless laptop while moving from place to place without ever being (temporarily) disconnected

### ⑤ replication transparency

: **resources may be replicated to increase availability or to improve performance by placing a copy close to the place where it is accessed**

- All replicas have the same name
- Support location transparency

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## 1.2.2. Transparency

### ⑥ concurrency transparency

: **hide that a resource may be shared by several competitive users**

- Issue: concurrent access to a shared resource leaves that resource in a consistent state
  - Consistency can be achieved through locking mechanisms

### ⑦ failure transparent

: **a user does not notice that a resource fails to work properly, and that the system subsequently recovers from that failure**

- Difficulty in masking failures lies in the inability to distinguish between a dead resource and a painfully slow resource

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## 1.2.2. Transparency

### ⑧ persistence transparency

: **masking whether a resource is in volatile memory or or perhaps somewhere on a disk**

- In object-oriented databases user is unaware that the server is moving state between primary and secondary memory
- **Degree of Transparency**
  - Trade-off between a high degree of transparency and the performance of a system

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## 1.2.3. Openness

- **Open distributed system is a system that offers services according to standard rules that describe the syntax and semantics of these services**
  - In computer networks
    - : standard rules govern the **format contents, meaning of messages sent and received**
      - Formalized in **protocols**
  - In Distributed system
    - : services are specified through interfaces (IDL: interface Definition Language)
      - Specify the names of the functions that are available together with type of the **parameters, return values, possible exceptions**
      - Hard part: the semantics of interfaces (by means of natural language)
        - **informal way**

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## 1.2.3. Openness

- Once properly specified, an interface definition
  - Allows an arbitrary process to talk another process through that interface
  - **Allows two independent parties to build different implementations of those interface**
- **Proper specifications** are complete & neutral
  - **Complete: everything that is necessary to make an implementation has indeed been specified** (in real world not at all complete)
  - **Neutral: specifications do not prescribe what the implementation should look like they should be neutral**

Important for interoperability and portability

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## 1.2.3. Openness

- **Interoperability**

- Two implementations of systems or components from different manufacturers can co-exist and work together by merely relying on each other's services as specified by a common standard

- **Portability**

- An application developed for a distributed system A can be executed, without modification, on a different distributed system B that implements the same interfaces as A

- **Flexibility**

- It should be easy to configure the system out of different components possibly from different developers
- Easy to add new components or replace existing ones without affecting those components that stay in place

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## 1.2.3. Openness

- **Separating Policy from Mechanism**

- To achieve flexibility, the system is organized as a collection of relatively small and easily replaceable or adaptable components
  - Implies that should provide definitions of the high-level interface and the internal parts of the system (how parts interact)
  - A component does not provide the optional policy for a specific user or application  
ex : caching in WWW

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## 1.2.3. Openness

- **Ex: caching policy**

- Browsers allow a user to adapt their caching policy by specifying the size of cache, whether a cached document should always be checked for consistency, or only once per session
- But, the user can not influence other caching parameters, how long a document may remain in the cache, or which document should be removed when the cache fills up. Impossible to make caching decisions based on the content of document.

- **We need a separation between policy& mechanism**

- Browser should ideally provide facilities for only storing documents (mechanism)
- Allow users to decide which documents are stored and for how long (policy)
- In practice, this can be implemented by offering a rich set of parameters that the use can set dynamically
- Even better is the a user can implement his own policy in the form of a component that can be plugged into the browser. the component must have an interface that the browser can understand.

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## 1.2.4 Scalability

- **Measured 3 different dimensions**

- ① **Size** : can easily add more users and resources to the system
- ② **Geographically scalable system** : the users and resources may lie for apart
- ③ **Administratively scalable** : it can be easy to manage even if it spans many independent administrative organizations.

- **Some loss of performance as the system scales up**

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# Scalability problems

## 1. Size

### : Confronted with the limitations of

- ① Centralized services : A single server for all users
  - problem : the server become a bottleneck as the number of user grows
  - Unavoidable using a single server : service for managing highly confidential information such as medical records, bank accounts.....
  - Copying the server to several locations to enhance performance → Vulnerable to security attack
- ② Centralized Data : A single on-line telephone book
  - problem : saturate all the communication lines into and out of a single database

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### ③ Centralized Algorithm : Doing routing based on complete information.

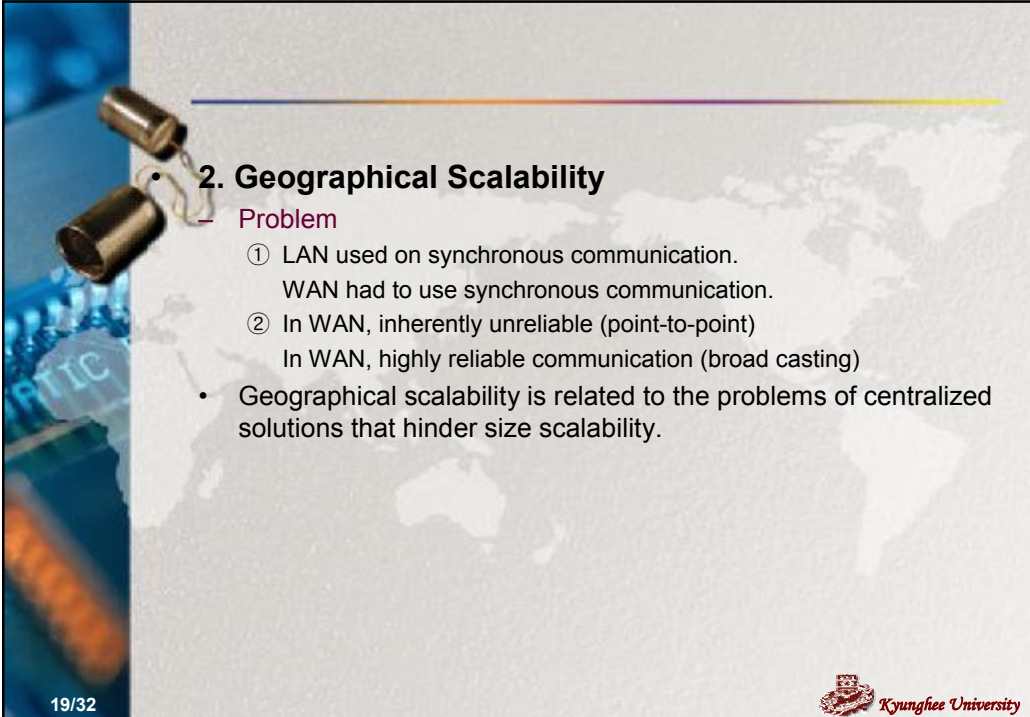
- Problem : theoretical point of view the optimal way to do routing in collect complete information about load on all machines and lines and then run a graph theory algorithm to compute all the optimal route.
- Problem : messages would overload part of network
- Solution : Decentralized Algorithms should be used

#### Characteristics

- ① No machine has complete information about the system state.
- ② Machines make decisions based only on local information.
- ③ Failure of one machine does not ruin the algorithms.
- ④ There are no implicit assumption that a global check exists.
  - Clock synchronization is tricky in WAN


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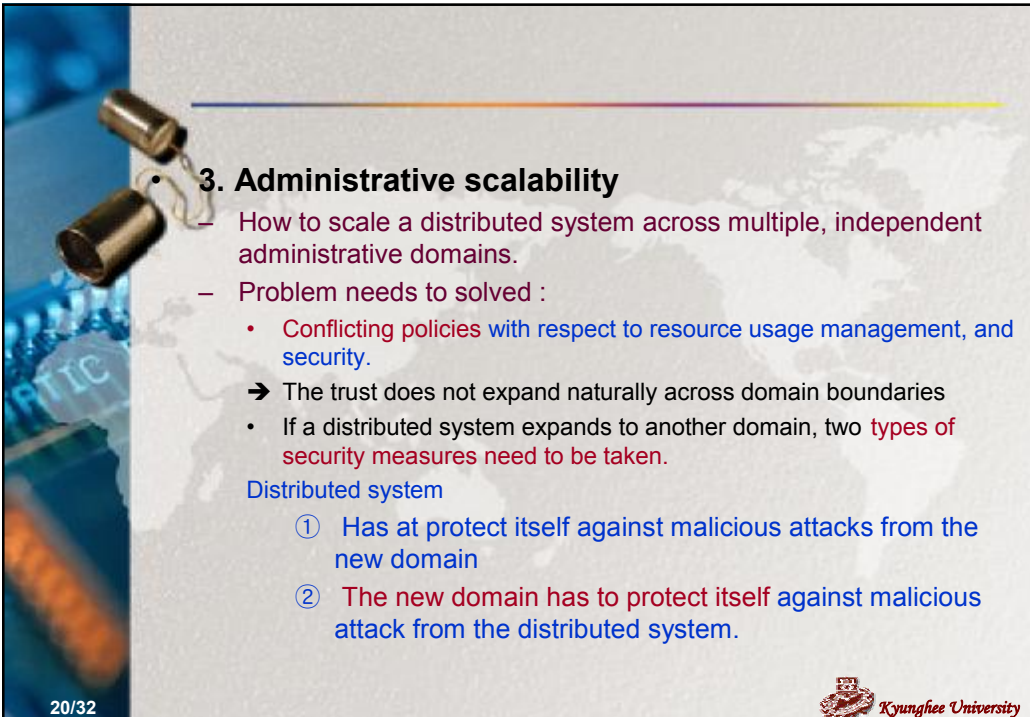




## • 2. Geographical Scalability

- Problem
  - ① LAN used on synchronous communication.  
WAN had to use synchronous communication.
  - ② In WAN, inherently unreliable (point-to-point)  
In WAN, highly reliable communication (broad casting)
- Geographical scalability is related to the problems of centralized solutions that hinder size scalability.

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## • 3. Administrative scalability

- How to scale a distributed system across multiple, independent administrative domains.
- Problem needs to solved :
  - **Conflicting policies with respect to resource usage management, and security.**
  - The trust does not expand naturally across domain boundaries
  - If a distributed system expands to another domain, two **types of security measures need to be taken.**

Distributed system

- ① Has at protect itself against malicious attacks from the new domain
- ② **The new domain has to protect itself against malicious attack from the distributed system.**

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## Scaling Techniques

- ① Hiding communication latencies
- ② Distribution
- ③ Replication

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### ① Hiding communication latencies

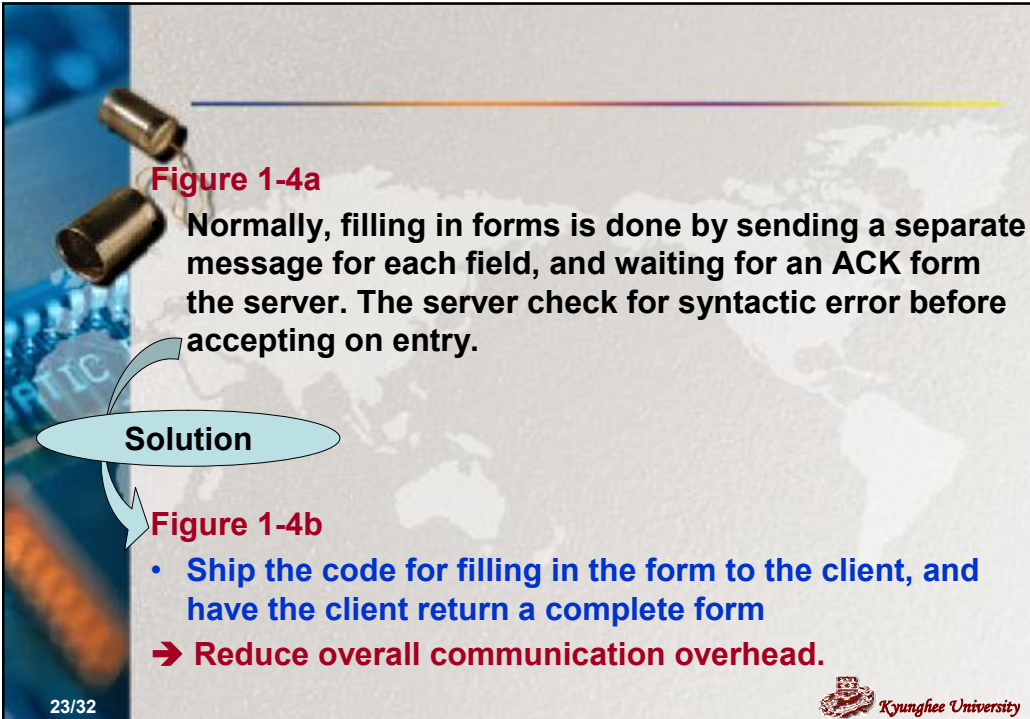
- **Solution** : Try to avoid waiting for responses to remote service requests as much as possible.
  - Asynchronous communication is a solution.

**In reality, many applications not use of asynchronous communication**

- Example : Interactive applications.
  - by moving part of computations which usually done at the server to the client process.
  - Accessing DB case Figure 1-4.

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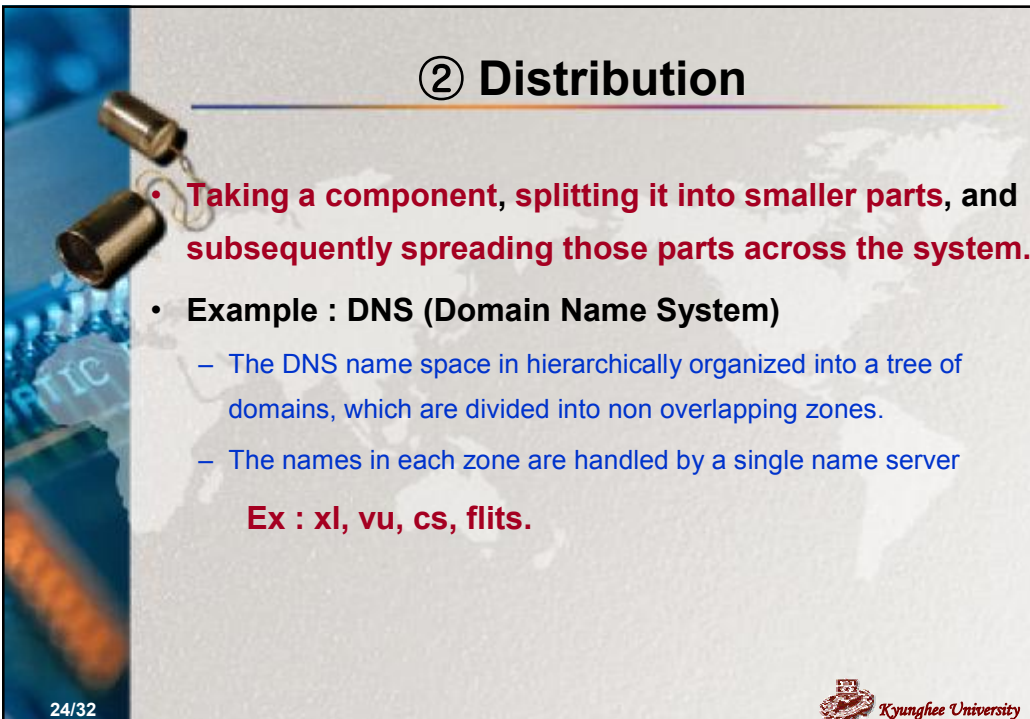
**Figure 1-4a**  
Normally, filling in forms is done by sending a separate message for each field, and waiting for an ACK from the server. The server check for syntactic error before accepting on entry.

**Solution**

**Figure 1-4b**

- Ship the code for filling in the form to the client, and have the client return a complete form
- Reduce overall communication overhead.


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## ② Distribution

- Taking a component, splitting it into smaller parts, and subsequently spreading those parts across the system.
- Example : DNS (Domain Name System)
  - The DNS name space is hierarchically organized into a tree of domains, which are divided into non overlapping zones.
  - The names in each zone are handled by a single name server

**Ex : xl, vu, cs, flits.**

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### ③ Replication

- Scalability problems often appear in the form of performance degradation, it is a good idea to actually replicate components across a distributed system.
- **Replication increases availability and load balance.**
- **Having a copy nearby can hide much of the communication latency problems.**
- Caching is a special form of replication.
- **Leads to consistency problems.**

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### 1.3 Hardware Concept

Even though distributed systems consist of multiple CPUs there are several ways the H/W can be organized  
=> How they are interconnected & communicate

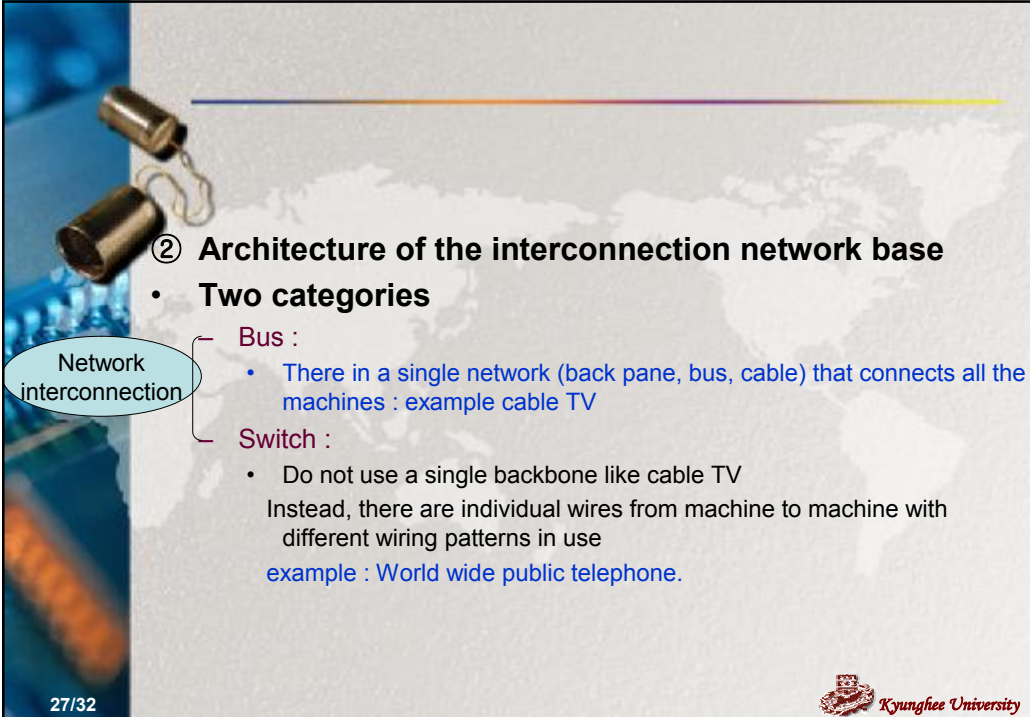
#### ① Classification

- Shared Memory => multiprocessors :
  - a single physical address space that is shared by all CPUs
- Non shared Memory => Multicomputers :
  - Every machine has its own private memory.
  - Common example : a collection of PC connected by a network

memory

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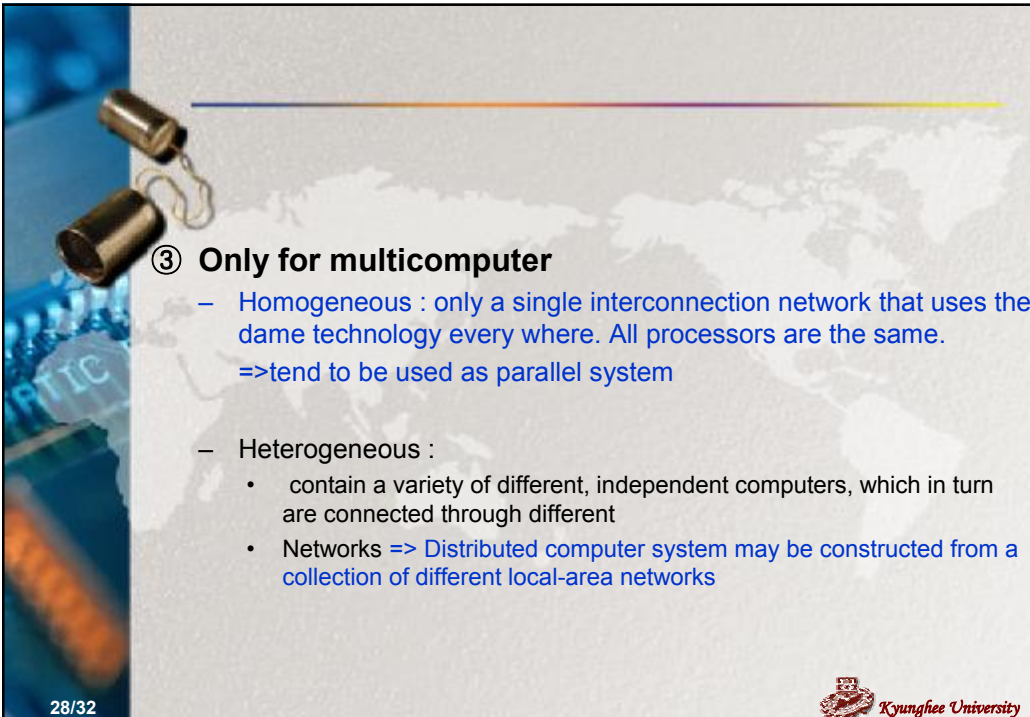



Network interconnection

## ② Architecture of the interconnection network base

- **Two categories**
  - **Bus :**
    - There in a single network (back pane, bus, cable) that connects all the machines : example cable TV
  - **Switch :**
    - Do not use a single backbone like cable TV
    - Instead, there are individual wires from machine to machine with different wiring patterns in use
    - example : World wide public telephone.


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## ③ Only for multicomputer

- **Homogeneous :** only a single interconnection network that uses the same technology every where. All processors are the same.  
=>tend to be used as parallel system
- **Heterogeneous :**
  - contain a variety of different, independent computers, which in turn are connected through different
  - Networks => Distributed computer system may be constructed from a collection of different local-area networks

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## 1.3.1 Multiprocessors

- Share a single key property : **all the CPUs have direct access to the shared memory.**
- **Coherent** : since there is only one memory, if CPU A writes a word to memory and then CPU B reads that word back a microsecond later, B will get the value just written.
- **Problem** : with as few as 4 or 5 CPUs, the bus will usually be **overloaded and performance will drop drastically**

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- **Solution** : is to add a high-speed cache memory between the CPU & the bus.  
[Fig 1-7] -> reduce bus traffic  
**hitrate** : the probability of success (the word requested is in the cache)  
ex: cache size : 512KB to 1MB are common  
hit rate 90% or more

cache

- Another problem of cache : **memory incoherent**

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**CPU A**      **CPU B**      **Memory**

Cache ~~3~~ 4      Cache 3      ~~3~~ 4

Bus

1. CPU A & B each read the same word into their respective caches
2. CPU A read 3 -> overwrite 4
3. CPU B read 3 -> ~~3~~ in the oed value <- not the value A just wrote

∴ incoherent : the system is difficult to program

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• **Another problem of bus-based Multiprocessor**


↓

**limited scalability** even when using “cache”

- Crossbar switch [refer to Fig 5.8-3]
- **The virtue of the crossbar switch**
  - Many CPUs can be accessing memory at the same time although if two CPUs try to access the same memory simultaneously, one of them will have to wait
- **Downside of the crossbar switch**
  - Exponential growth of crosspoint switch number if # of CPU(n) grow large. ( $n^2$ )
- **Omega network (require fewer switch) [Fig 1-8-6]**
  - With proper settings of the switches, every CPU can access every memory

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## • Drawback of Switching Network

- There may be several switching stages between the CPU and Memory
- -> Consequently, to ensure low latency between CPU & memory, switching has to be extremely fast, which is expensive
- reduce the cost of switching
- Hierarchical system : NUMA (NonUniform Memory Access) machine
- Some memory is associated with each CPU
- Each CPU can access its own local memory quickly, but accessing anybody else memory is slower
- Another complication :  
placement of the programs and data becomes critical in order to make access go to the local memory


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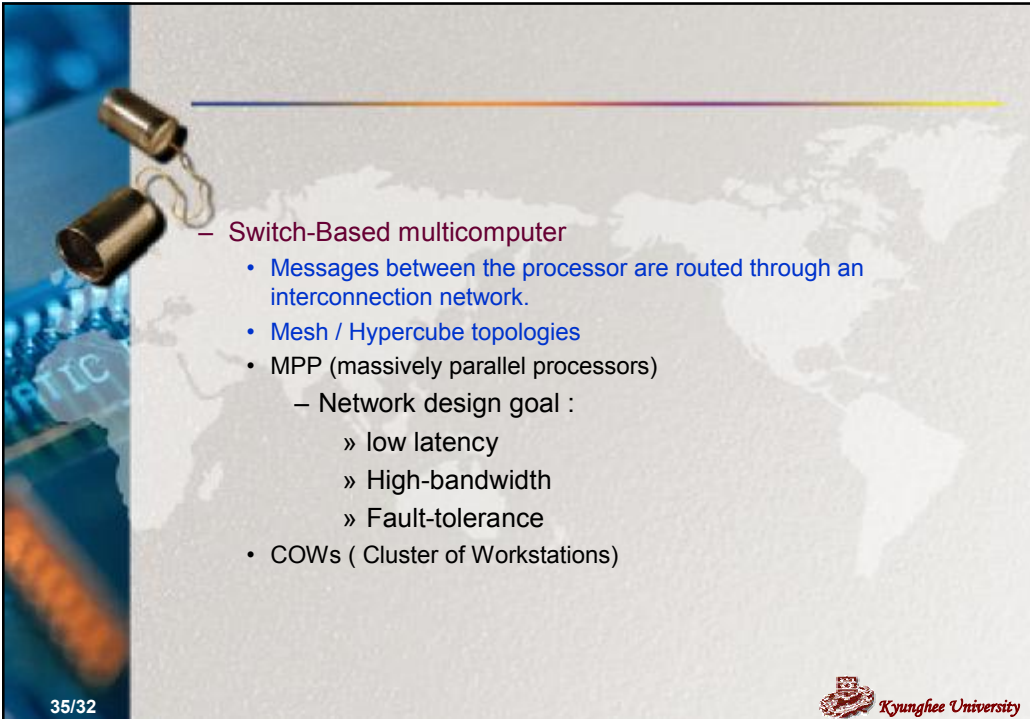


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## 1.3.2. Homogeneous Multicomputer Systems

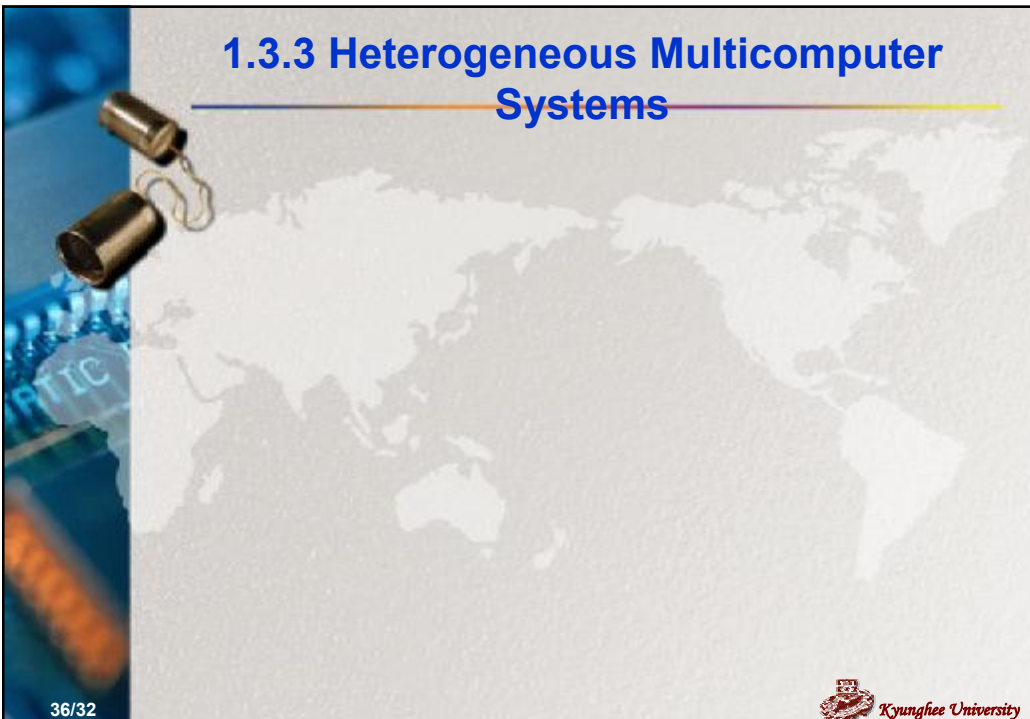

- **Relatively easy to build compare to Multiprocessors**
- **Each CPU has a direct connection to its own local memory**
- **How the CPUs communicate with each other ( CPU-to-CPU communication)**
- **Volume of traffic is much lower than that of CPU-to-memory**
  - SAN (System Area Networks) : connected through a single interconnection network
  - Bus-based multicomputer
    - The processors are connected through a shared multiaccess network
    - Limited scalability
    - Broad-cast

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- **Switch-Based multicomputer**
  - Messages between the processor are routed through an interconnection network.
  - Mesh / Hypercube topologies
  - MPP (massively parallel processors)
    - Network design goal :
      - » low latency
      - » High-bandwidth
      - » Fault-tolerance
  - COWs ( Cluster of Workstations)

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## 1.3.3 Heterogeneous Multicomputer Systems

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## 1.4. Software Concepts

- **Distributed system :**

- Matter of software not matter of HW
- Act as resource managers for the underlying H/W
- Attempt to hide the intricacies and heterogeneous nature of underlying hardware by providing a virtual machine on which applications can be easily executed.

- **OS for distributed computers**

- Tightly coupled system :
  - Try to maintain a single, global view of the resources it manages : DOS (Distributed OS)
  - >need for managing multiprocessors and homogeneous multicomputers
- Loosely-coupled system : Collection of computers each running their own operating system : NOS (Network OS)
  - >local services are made available to remote clients

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※ Enhancements to the services of network OS are needed such that better support for distribution transparency -> middleware :

lie at the heart of modern distributed system

※ Figure 1-10 : overview between DOS, NOS, and MW

System	Description	Main goal
DOS	Tightly-coupled OS for multiprocessor and homogeneous multicomputers	Hide & manage Hardware resource
NOS	Loosely-coupled OS for heterogeneous multicomputers (LAN and WAN)	Offer local services to remote clients
Middlew are	Additional layer a top of NOS implementing general-purpose services	Provide distribution transparency

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## 1.4.1. DOS

- Uniprocessor OS
- Multiprocessor OS
- Multicomputer OS
- Distributed Shared Memory Systems

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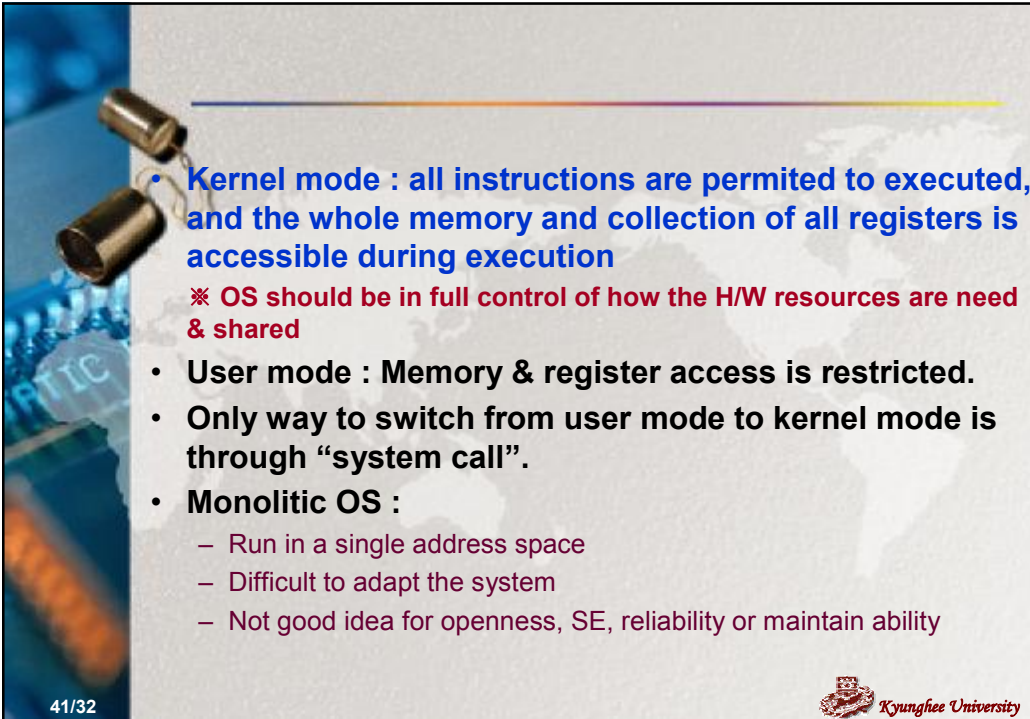


## Uniprocessor OS

- Allow uses/applications an easy way of sharing resources  
(CPU, Main Memory, Disks, peripheral device)
- Virtual machine : To an application, it **appears as if it has its own resources**, and that there may be **several applications executing on the same system at the same time**, each with **their own set of resources**  
**sharing resources : applications are protected from each other**


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- **Kernel mode** : all instructions are permitted to executed, and the whole memory and collection of all registers is accessible during execution
  - ※ OS should be in full control of how the H/W resources are need & shared
- **User mode** : Memory & register access is restricted.
- **Only way to switch from user mode to kernel mode is through “system call”.**
- **Monolithic OS** :
  - Run in a single address space
  - Difficult to adapt the system
  - Not good idea for openness, SE, reliability or maintain ability

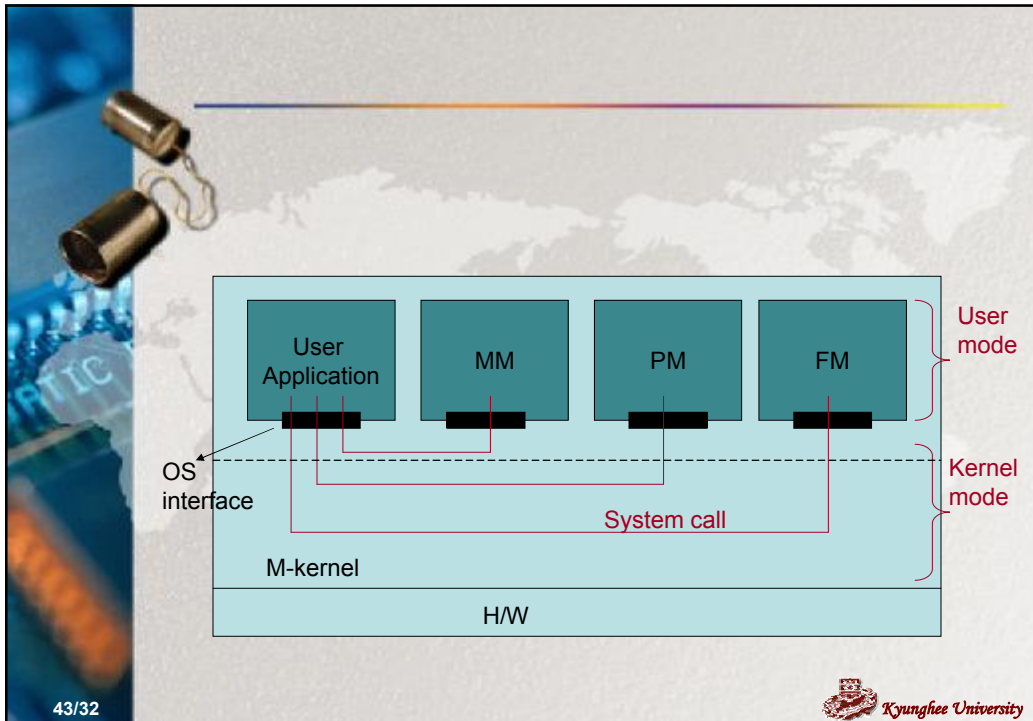
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- **Microkernel OS** :
  - Containing only the code that must execute in kernel mode
  - Only contain the code for setting device registers, switching the CPU between processes, manipulating MMU, and capturing hardware interrupts.
  - Contains the code to pass system calls to calls on the appropriate user-level OS modules, and to return their results.

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- **Main Benefits to using Microkernels**
  - Flexibility
    - A large part of OS is executed in user mode, it is relatively easy to recompile or re-install the entire system
    - User level modules can be place on different machines
  - Disadvantages
    - Different from the way current OS work (meets massive resistance)
    - Extra communication cost ->performance loss

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## Multiprocessor OS

- An important is to support for multiple processors having access to a shared memory.
- Data have to be **protected** against concurrent access to guarantee **consistency** but can't easily handle multiple CPUs since they have been designed as monolithic programs that **can be executed only with a single thread of control** => need redesigning and reimplementing the entire kernel

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### • Goal of multiprocessor OS :

- To support high performance through multiple CPUs
- Is to make the # of CPUs transparent to the application.
- communication between different part of applications uses the same primitives as these in multitasking uniprocessor OS.
- All communication is done by manipulating data at shared memory locations => protect that data against simultaneous access  
=> protection is done through synch primitives : semaphore / Monitor
- ※ Explain Semaphore / Monitor

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- **Semaphore :**
  - Error-prone except when need for simply protecting shared data
  - Problem : easily lead to unstructured code (goto statement)
- **Monitor :**
  - Programming – language construct similar to an object in O-based programming
  - Problem : they are programming – language constructs
    - java provides a notion of monitors by essentially allowing each object to protect itself against concurrent access through synchronized statements, and operations **wait** and **notify** on objects.

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## Multicomputer OS

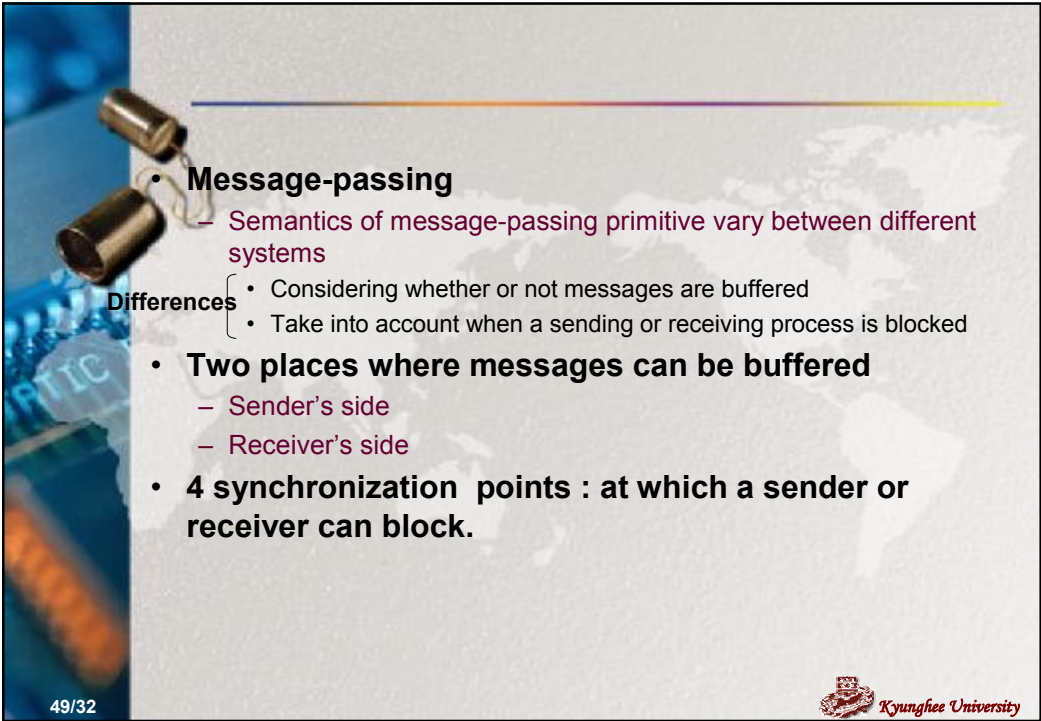
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- Different (totally) structure and complexity than multiprocessor OS
- Means of communication : **Message passing** (not enough for shared memory)
- [Fig 1-14]
  - Each mode has its own kernel containing modules for managing local resources such as memory, the local CPU, a local disk, and soon.
- Each kernel support **parallel** and **concurrent execution** of various tasks
  - Software implementation of shared memory =>by means of message passing
  - Assigning a task to a processor
  - Masking transparent storage
  - General interprocess communication

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- **Message-passing**
  - Semantics of message-passing primitive vary between different systems
- **Differences**
  - Considering whether or not messages are buffered
  - Take into account when a sending or receiving process is blocked
- **Two places where messages can be buffered**
  - Sender's side
  - Receiver's side
- **4 synchronization points : at which a sender or receiver can block.**

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